## Signal Animator ABS MODE TRUTH TABLE

Inputs are active low. With nothing connected, they will be held at a high level and the driving circuit must connect it to ground to provide an active input. Low inputs on the table are indicated with a zero (0), high inputs with a (1), and inputs that do not matter are indicated with a blank field.

The DCA (Danger/Clear/Approach) inputs are labelled **RD**, **YL**, **GN**, **R2**, and **Y2**, and are usually driven by occupancy detectors in ABS mode. When all are inactive (high), the signal display will be dark. Display will be lit when at least one of **GN**, **RD**, or **R2** inputs are active.

The **RD** and **R2** inputs indicate Danger and when either or both are active, a stop indication will be displayed, regardless of the state of the speed inputs, or the other DCA inputs. An occupancy detector for the block the signal is guarding entry into drives either of these inputs. The second input is provided for situations where an additional occupancy detector is necessary.

The **GN** input is used for approach lighting. If approach lighting is not used, and signal is always lit, a jumper can be used to permanently connect this input to ground. For approach lighting, this input is driven by an occupancy detector that detects the block that the train is in when it reaches the signal. When approach lighting is used, signal will be dark except when the block approaching the signal is occupied (**GN** input) or when the block it is protecting is occupied (**RD** or **R2** inputs).

The **YL** and **Y2** inputs indicate Approach and when either or both are active, but not when a Danger input is active, and will result in a "something to stop" indication being displayed, with the something being determined by the Entry speed inputs. The second input is provided for situations where an additional occupancy detector is necessary.

**EL**, **EM**, **ES**, and **ER** are the Entry speed inputs, indicating Limited, Medium, Slow, and Restricting speeds respectively. Their state indicates the speed restriction for the block the signal is protecting entry to.

**AL**, **AM**, **AS**, and **AR** are the Approach speed restricting inputs, indicating Limited, Medium, Slow, and Restricting speeds respectively. Their state indicates what speed the next signal should be approached at.

On the following truth table, RD and R2 are represented with one column labelled R. When the value is 1, both inputs must be 1. When the value is 0, either or both inputs are low. The same applies for YL and Y2 being represented under Y.

			Cianal Indiantian									
ΑV	GN	Y	Y R AL AM AS AR EL EM ES E								ER	Signal Indication
	1		1									dark
		Inp	uark									

				G: 17 !: ::													
	AV	GN	Y	R	AL	nputs AM	AS	AR	EL	EM	ES	ER	Signal Indication				
"Stop" indications.				0 DCA	Provides rule 436 with Plate on mast  Rule 437: Stop and Proceed  Rule 439: Stop Signal												
cting tion.		0		1								0	Low signal output				
Restricting indication.	Е	ntry	speed	l inpu	÷.	Rule 436: Restricting Signal											
		0	0	1							0	1	ಿ ಕಿ				
nactive Is.	Entry speed inputs: ES active; ER <i>not</i> active.												Low signal output used for medium head  Rule 435: Slow to Stop				
e, RD i		0	0	1						0	1	1	Provides rule 421				
DCA inputs: GN and YL active, RD inactive. "Something to Stop" indications.		Entry speed inputs: EM active; ES and ER <i>not</i> active.											with Alate on mast  Rule 427: Medium to Stop				
and Y		0	0	1					0	1	1	1	8				
ıts: GN methin	En	ıtry sı	peed	input	s: EL	active	; EM,	ES, a	and E	R not	activ	/e.	Rule 421: Limited to Stop				
CA inpu	1	0	0	1					1	1	1	1	9 ° 8				
Ď				No	entry	speed	inpu	ts act	ive.				Rule 411: Clear to Stop				
ive,		0	1	1				0			0	1	dark				
S act			"Slo	w to I	Restri	cting"	indica	ation	is inv	alid.							
uts: E		0	1	1			0	1			0	1	S .				
ed inp g" indi	Approach speed inputs: AS active; AR <i>not</i> active.										Rule 434: Slow to Slow						
Entry speed inputs: ES active, Something" indications.		0	1	1		0	1	1			0	1	ឺ				
		App	roacl	n spe	ed inp	outs: A	M ac	tive;	AS no	ot act	ive.		Rule 433: Slow to Medium				
puts: only GN activ ER inactive. "Slow		0	1	1	0	1	1	1			0	1					
only ( active	Αŗ	proa	ch sp	eed ii	nputs	: AL ad	ctive;	AM a	and A	S not	activ	e.	Rule 432: Slow to Limited				
DCA inputs: only GN active; ER inactive. "Slow to		0	1	1	1	1	1	1			0	1	Low signal output used for medium head				
DCA	No Approach speed inputs active.											Rule 431: Slow to Clear					

	AV	GN	Y	R	AL	АМ	AS	AR	EL	ЕМ	ES	ER	Signal Indication		
ive, s.		0	1	1				0		0	1	1	Provides <b>rule 420</b> with \( \sum_{plate} \) plate on mast		
EM active, dications.			Α	ppro	Rule 426: Medium to Restricting										
outs: E g" indi		0	1	1			0	1		0	1	1	<u>, 20</u>		
DCA inputs: only GN active; Entry speed inputs: EM activ ES and ER inactive. "Medium to Something" indications.		App	roacl	n spe	Rule 425: Medium to Slow										
ntry sp i to So		0	1	1		0	1	1		0	1	1	8		
tive; E ledium	Approach speed inputs: AM active; AR and AS <i>not</i> active.												Rule 424: Medium to Medium		
GN active. "P		0	1	1	0	1	1	1	1	0	1	1			
inputs: only GN and ER inactive.	Approach speed inputs: AL active; AR, AS, and AM <i>not</i> active.												Rule 423: Medium to Limited		
inputs and El		0	1	1	1	1	1	1	1	0	1	1	Provides rule 416 with b plate on mast		
DCA		No	Appr	oach	spee	d restr	iction	inpu	ts are	e acti	ve.		Rule 422: Medium to Clear		
, EM,		0	1	1				0	0	1	1	1	<b>\$</b>		
EL active, indications			Α	ppro	ach s	peed in	nputs	: AR	active	e.			Rule 420: Limited to Restricting		
		0	1	1			0	1	0	1	1	1	<b>3</b>		
ed inpu methir		App	roacl	n spe	ed in	puts: A	AS ac	tive;	AR no	ot act	ive.		Rule 419: Limited to Slow		
ry sper I to So		0	1	1		0	1	1	0	1	1	1	8		
/e; Ent Limited	Αp	proa	ch sp	eed ir	nputs	: AM a	ctive	; AS a	and A	R not	activ	/e.	Rule 418: Limited to Medium		
N activ		0	1	1	0	1	1	1	0	1	1	1	3		
DCA inputs: only GN active; Entry speed inputs: ES, and ER inactive. "Limited to Something"	Арр	roach	spee	ed inp	uts: A	AL activ	ve; Al	M, AS	, and	AR n	ot act	ive.	Rule 417: Limited to Limited		
nputs:		0	1	1	1	1	1	1	0	1	1	1	8		
DCA in ES,		No	Appr	oach	spee	d restr	iction	inpu	ts are	e acti	ve.		Rule 416: Limited to Clear		

	AV	GN	Y	R	AL	АМ	AS	AR	EL	EM	ES	ER	Signal Indication		
		0	1	1				0	1	1	1	1	Low signal output Used for medium head		
	Approach speed inputs: AR active.												Rule 410: Clear to Restricting		
	1	0	1	1			0	1	1	1	1	1	° 8 8		
		App	roacl	n spe	ed in	Rule 409: Clear to Slow									
	0	0	1	1			0	1	1	1	1	1	° 3 3		
DCA inputs: only GN active; no entry speed inputs active. "Clear to Something" indications.	AV	active	; Apı	oroac	h spe	ive.	Rule 414: Advance Clear to Slow								
inputs S.	1	0	1	1		0	1	1	1	1	1	1	Provides <b>rule 406</b> with plate on mast High signal output used		
speed	Αŗ	Approach speed inputs: AM active; AS and AR <i>not</i> active.											r for medium head Medium signal output used for low head Rule 407: Clear to Medium		
o entry ng" ind	0	0	1	1		0	1	1	1	1	1	1	ြီး ရှိ ရှိ		
only GN active; no entry speed in "Clear to Something" indications.			AV ac	tive;		ach sp			AM a	ctive;			Rule 413: Advance Clear to  Medium		
y GN ac	1	0	1	1	0	1	1	1	1	1	1	1	High signal output used for medium head lead for bedum signal output used for low head.  Rule 406: Clear to Limited		
ts: only	App	roach	spee	d inp	uts: A	AL activ	ve; Al	M, AS	, and	AR n	ot act	ive.			
A inpu	0	0	1	1	0	1	1	1	1	1	1	1			
DC		AV active; Approach speed inputs: AL active; AM, AS, and AR <i>not</i> active.											Rule 412: Advance Clear to Limited		
	0	0	1	1	1	0	1	1	1	1	1	1	9 9 8		
		Δ	V act	ive;	No Ap	proacl	h spe	ed in	outs a	active	١.		Rule 415: Advance Clear		
		0	1	1	1	1	1	1	1	1	1	1	To Stop		
			1	No Ap	proad		Rule 405: Clear Signal								

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